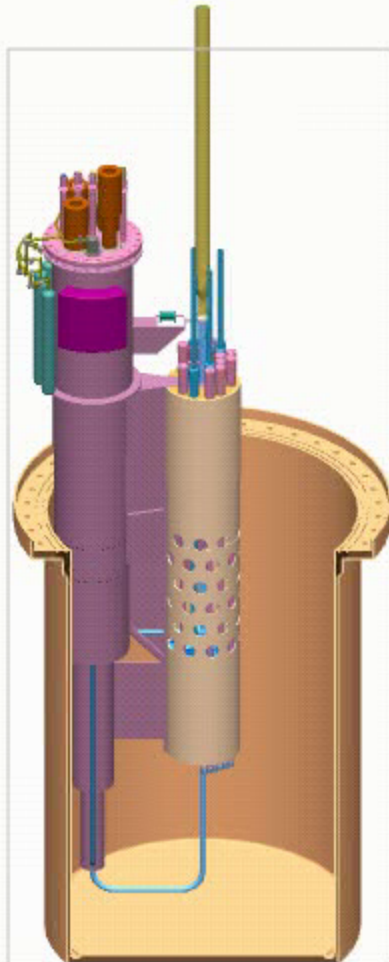


Design and R&D support of the XT-ADS Spallation Target Loop

Paul Schuurmans

on behalf of the XT-ADS spallation target design

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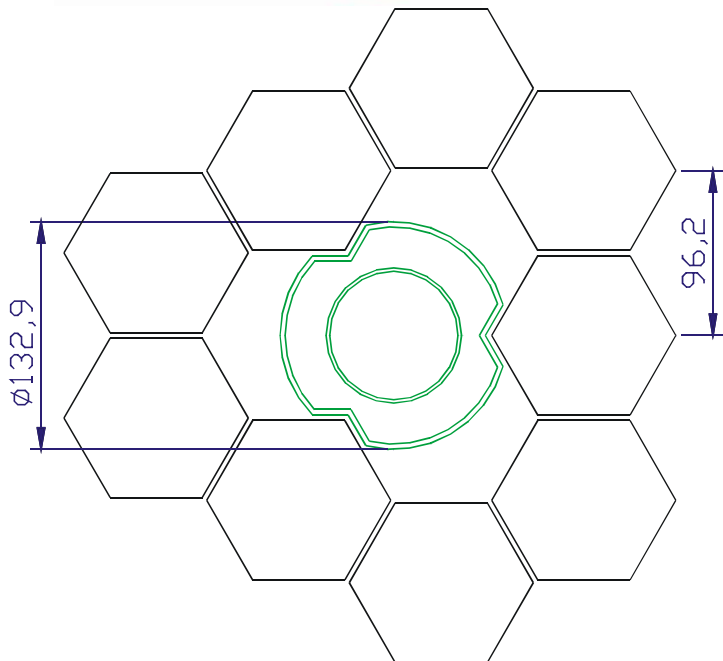
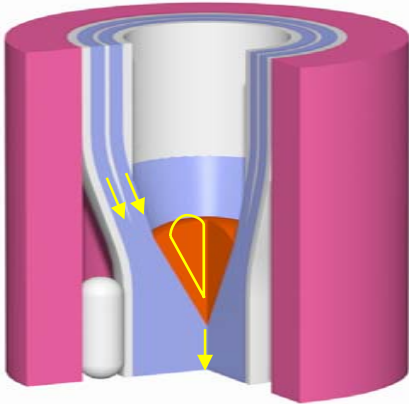


- Conceptual properties
- Loop configuration
- Layout
- Spallation target
- Spallation loop components
- Conclusions

- Target tasks & boundary conditions

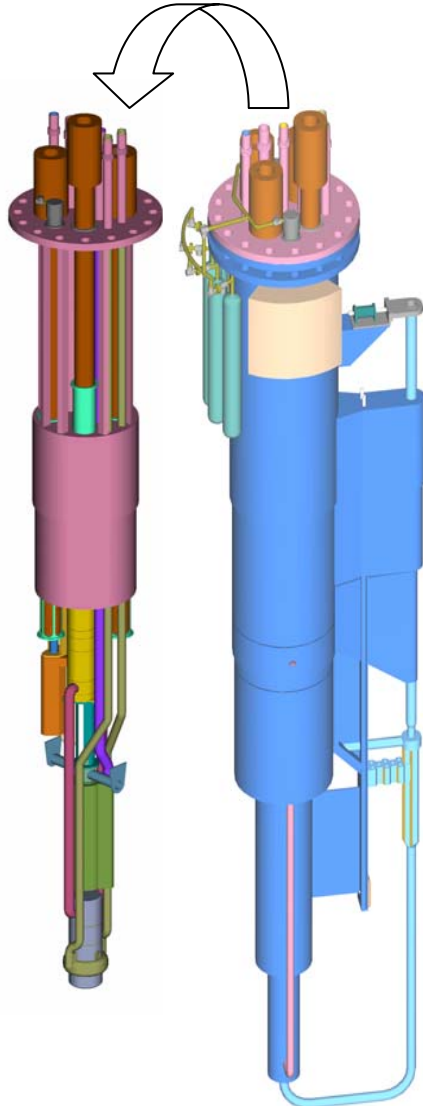
- Produce $\sim 10^{17}$ neutrons/s to feed subcritical core @ $k_{\text{eff}} \approx 0.95$
- Accept 600 MeV x 2.5 mA proton beam (up to 4 mA for burn-up compensation)
- Evacuate deposited heat : 1-1.56 MW
- Space limitation: three central assemblies in core : 96.2 mm fuel assembly pitch
- Lifetime: > 1y
- Flexibility in use (XT ADS purpose as experimental irradiation machine)

Target Design : Conceptual properties



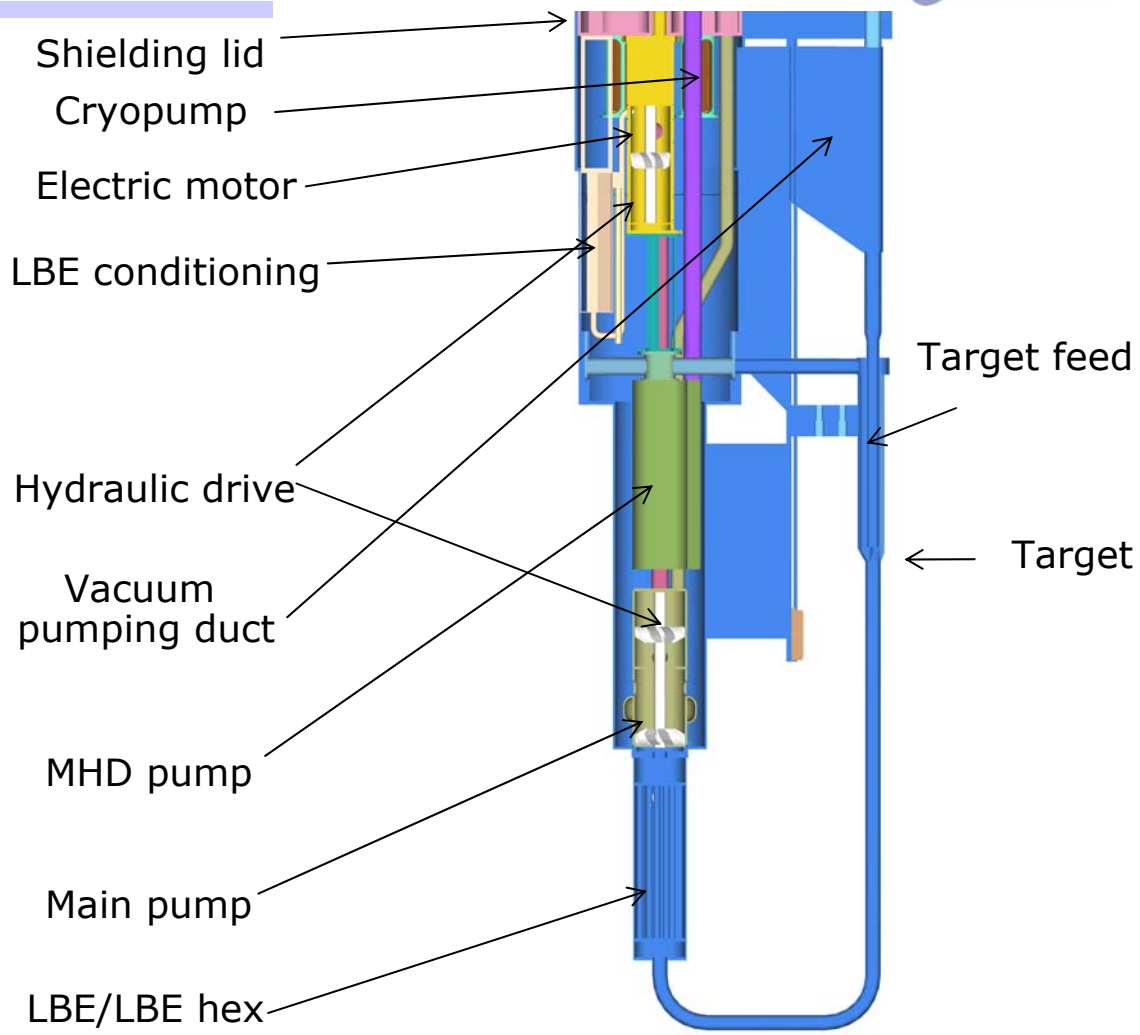
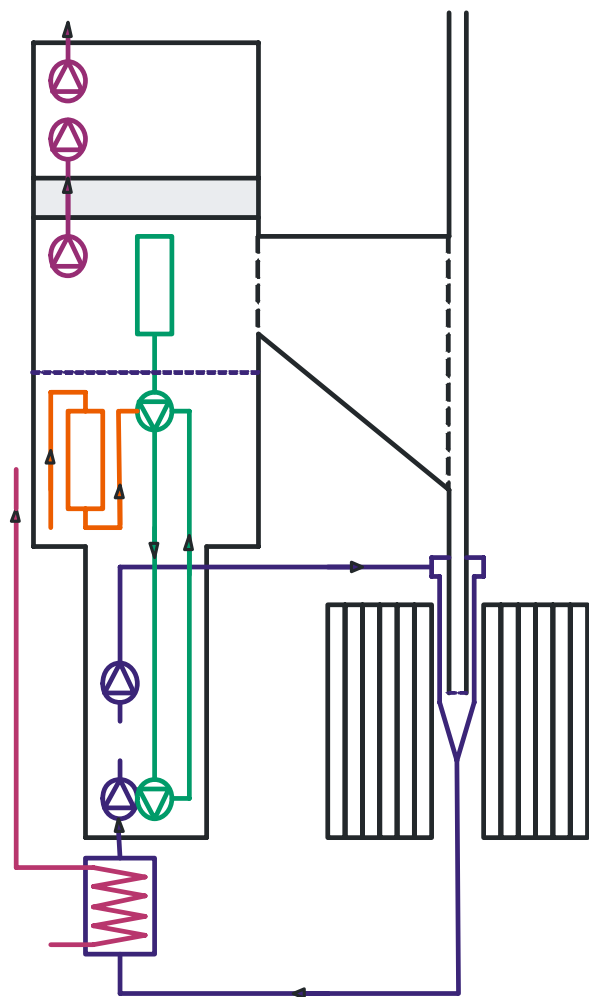
- **Windowless target**
 - Beam current density
- **Vertical coaxial confluent LBE flow**
 - Space consideration
 - Free surface formation
- **Target inflow via 3-feeder design**
- **Off axis LBE servicing**
 - Leave top & bottom of core free
 - ⇒ Accessibility
 - Loop away from high radiation zone
 - ⇒ Lifetime

Loop configuration

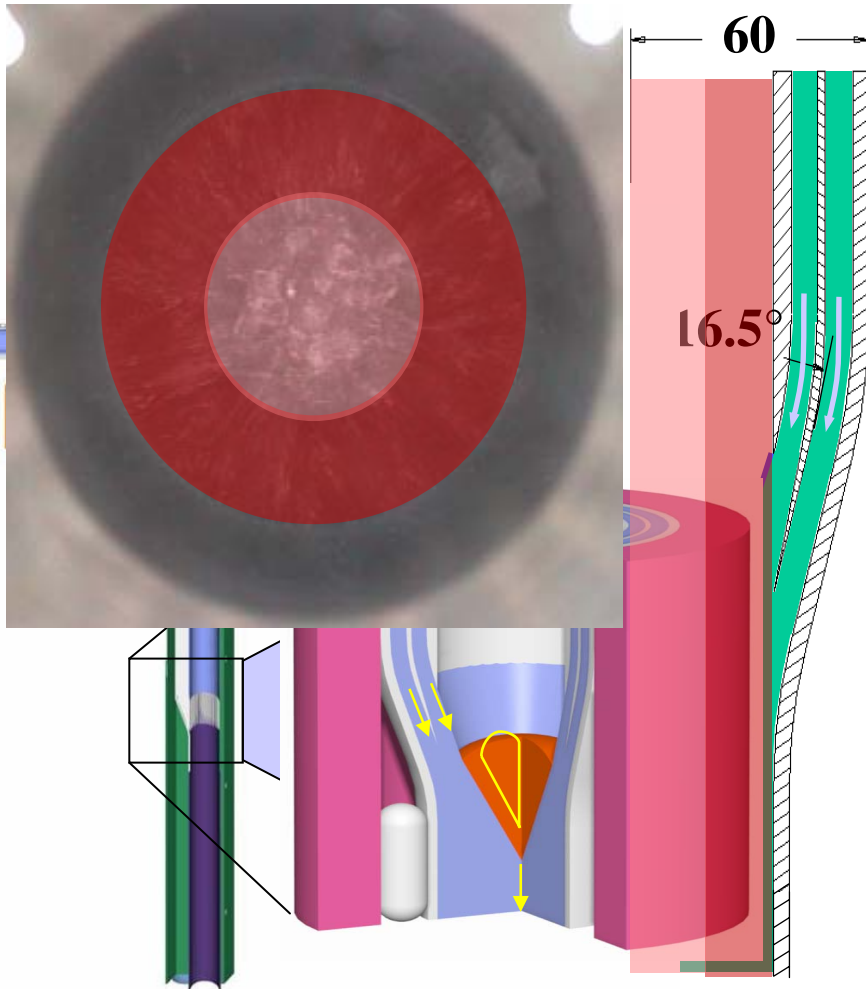


- **LBE flow & cooling**
 - Forced convection (10-20 l/s)
 - $T_{\max(\text{LBE surface})} = 450^{\circ}\text{C}$; $\Delta T < 100^{\circ}\text{C}$
 - Heat exchanger to main vessel coolant
- **Vacuum requirements**
 - Pressure above target $< 10^{-3} - 10^{-4}$ mbar
 - Confinement of volatile spallation products
- **LBE conditioning**
 - Corrosion inhibition, -Filtering
- **Service by remote handling**
 - Entire spallation unit removable from main vessel after core unloading
 - Separate sub-unit with all active elements

Loop layout schematics: MYRRHA draft 2

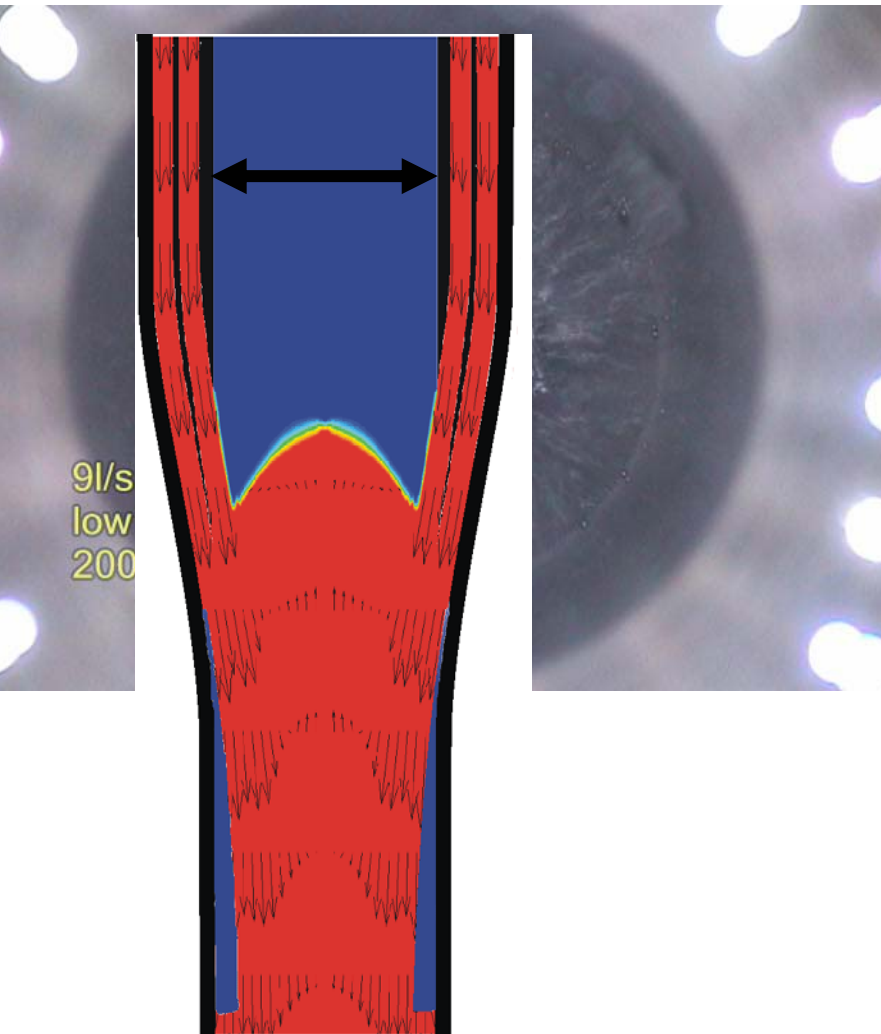


Spallation target



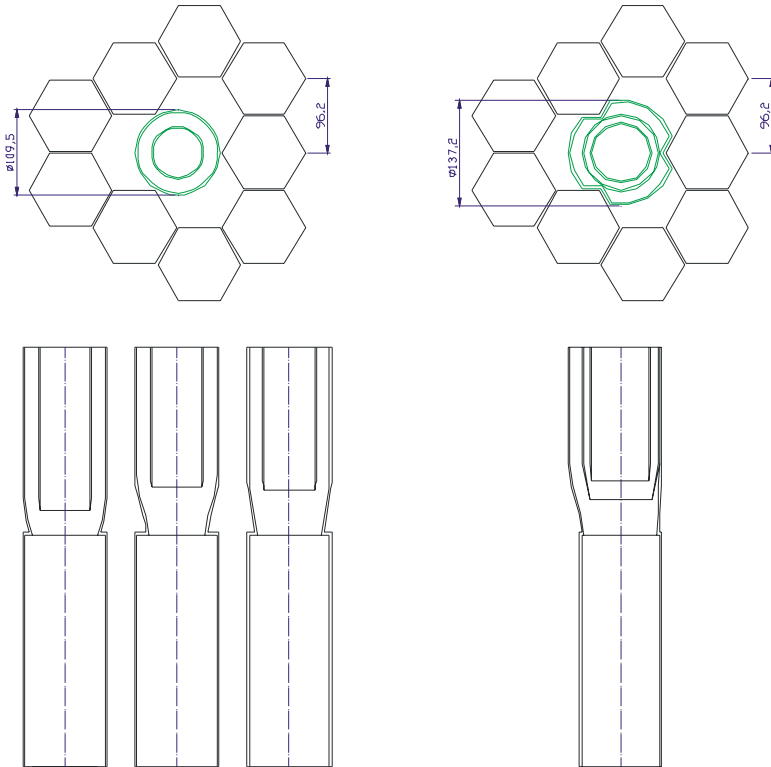
- Formation of target free surface
 - Confluence of Vertical coaxial flow
 - Level : balance inlet-outlet flow
 - Recirculation zone : in check
 - ♣ Level balance $\Delta h_{\max} = 3$ mm
 - Feedback necessary
 - ♣ LIDAR level detection
 - Proton beam distribution
 - ♣ Avoid recirculation zone heating

Spallation target



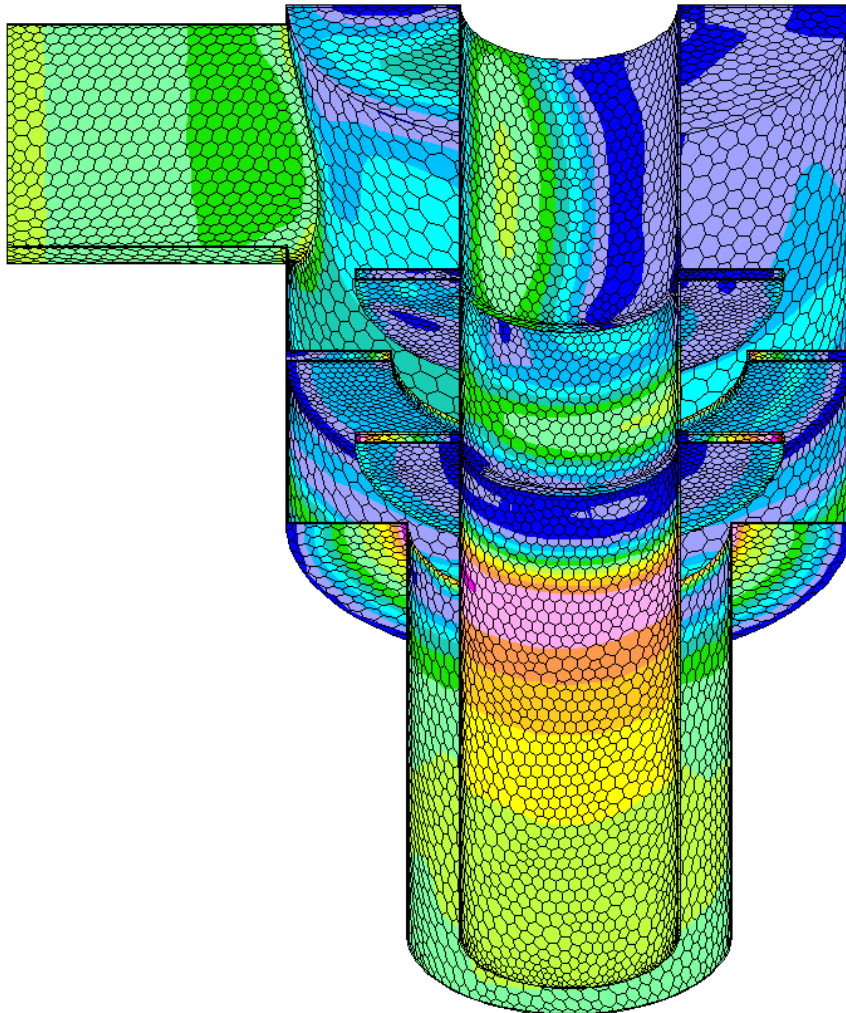
- Flow detachment required for stability → build into design
 - Void below target interface
 - inlet & outlet flow decoupled
 - allow sufficient space to accommodate beam-on beam-off volume change
 - ♣ LIDAR feedback can be slower
 - LBE evaporation : OK
 - Wall cooling : OK
- Increase target surface
 - Maximum use of 3 feeder lobes

Spallation target nozzle: next activities



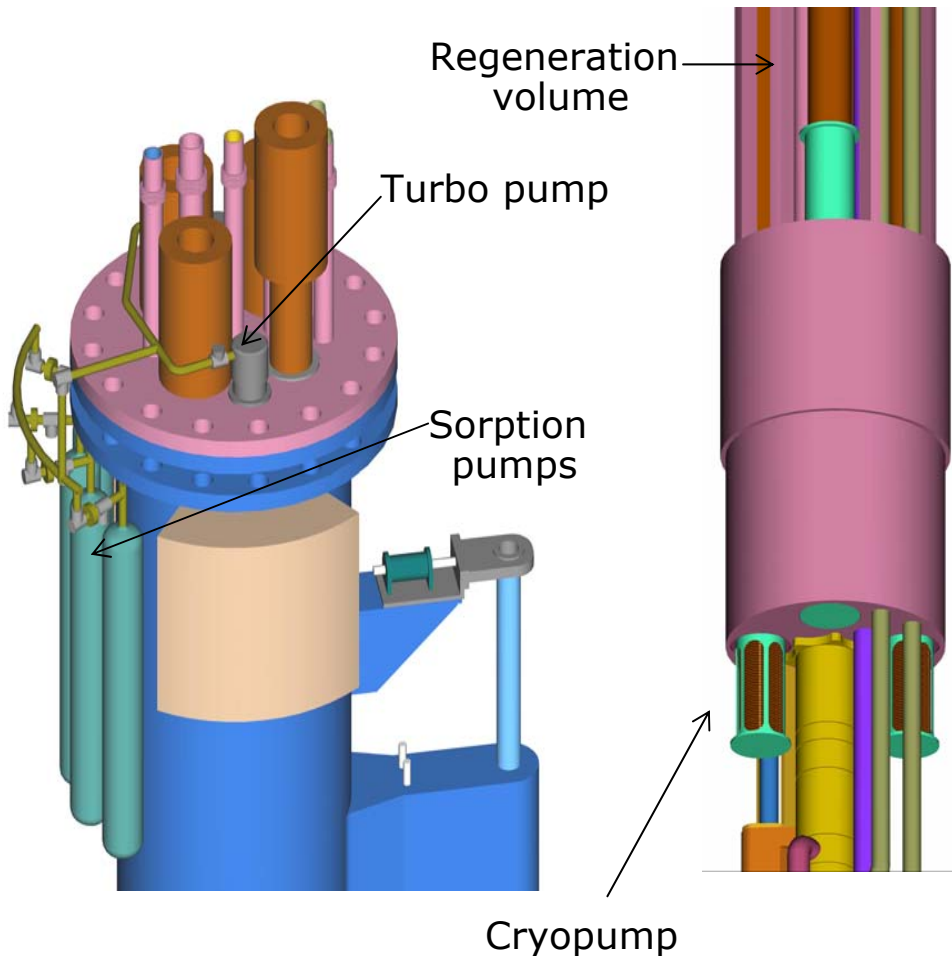
- Improvement of flow stability
 - Feeder :
Drag limitation vs accelerated flow
 - Position of detachment point vs confluence point
 - Swirl
- Check different design options with CFD
- Flow experiments on selected designs

Spallation target: feeder head



- Design feeder head
- CFD simulations
(V. Moreau CNRS, StarCD)
- Distribution plates
 - Destroy flow history
 - Homogeneous velocity distribution

Vacuum system : MYRRHA Draft 2



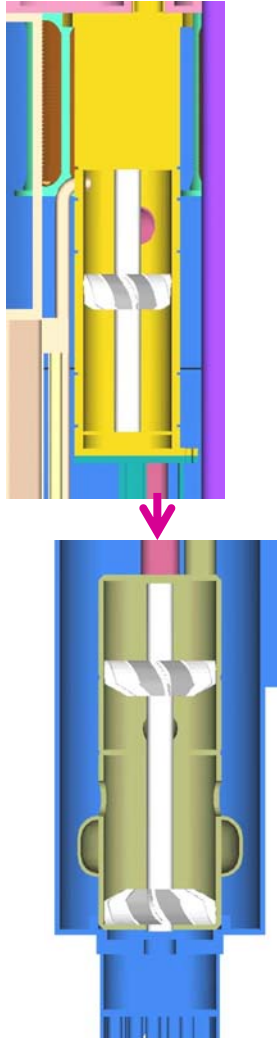
- Vacuum duct
- Cryopumps
 - 3 stage (H_2O , 77 K, 6K)
 - Active inner surface
 - 10000 l/s pumping speed
 - Hydraulically movable for regeneration
- Turbo pump
 - 400 l/s magnetic bearing
- Sorption pumps
 - Cooled zeolyte sorption (all condensables)
 - Active Zr-V-Fe getter (H, D,T)
 - Batch-wise removal

Spallation target Vacuum system



- Target shell : UHV
 - leaktightness
 - Cleanliness
- Maintaining vacuum above target : OK
- Vacuum pump effect of flowing LBE
 - diffusion of spallation products ?
 - to be quantified
- Free surface 1 (top)
 - Focus on spallation product confinement
 - Close off vacuum duct
 - Relax vacuum conditions (O 1 mbar)
 - Remove 6 K stage from cryopump →condensing station
- Regeneration during maintenance
 - Magnetic bearing Turbopump
 - Decay tank
 - Sorption pumps

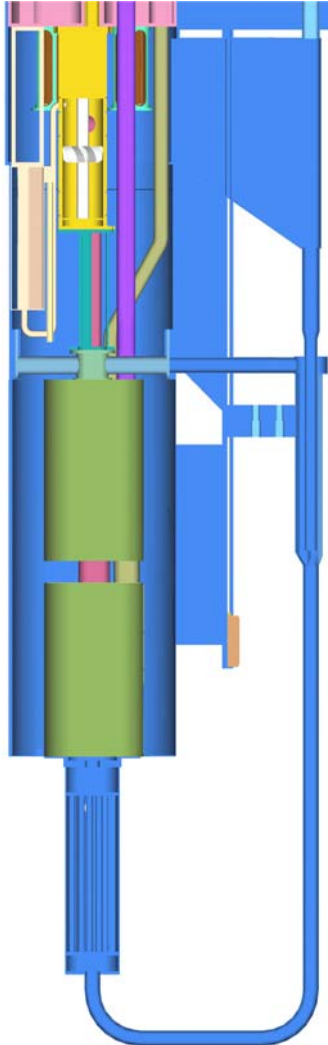
Circuit pumps : MYRRHA Draft 2



- MHD pump
 - Fast regulator (little inertia)
 - Modified “Megapie” type
 - ♣ lower slip ratio (LBE-field velocity match)
 - ♣ increased pump length (1.2 m)
 - short active periods during transients
- Main mechanical pump
 - restore potential LBE energy $\Delta p=4.4$ bar
 - driven by hydraulic drive
 - ♣ LBE from target loop
 - ♣ 10 kW canned electromotor, pump, turbine
 - LBE pump options
 - ♣ impeller : accelerating fluid
 - ♣ helix (screw-spindle) : volume displacement

Spallation target Components

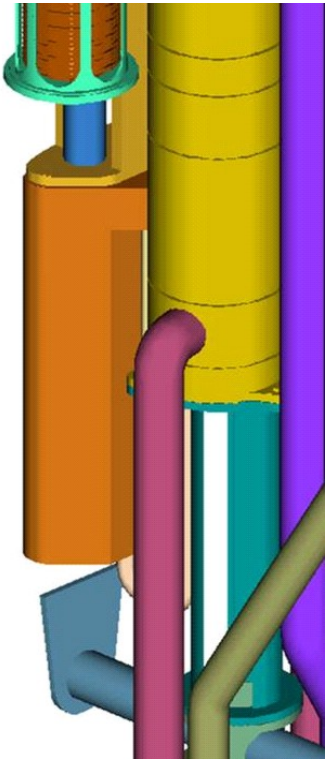
Circuit pumps



- Pump system
 - $Q=10-20$ l/s
 - total $\Delta p=4.4$ bar
- Detached flow in nozzle
 - Fast regulator not required
- Active feeder line MHD pump
- Active return line pump
 - Mechanical
 - ♣ impeller : accelerating fluid
 - ♣ helix (screw-spindle) : volume displacement
 - ♣ Hydraulic drive or long shaft
 - MHD
 - ♣ Efficiency
 - ♣ Space ($\phi \approx 800$ mm, $L \approx 1000$ mm)

Spallation target Components

Conditioning unit



- Oxygen control
 - sensors
 - Adding/removing oxygen (steady state)
 - ♣ continuous control via PbO pebble basket
 - ♣ most spallation products chemically reducing
 - ♣ exchange rate by temperature in conditioning vessel
 - Gross Oxygen reduction
 - ♣ gas treatment in-vessel only off-line
 - ♣ separate conditioning tank (heating issue)
- Filtering ?
 - magnetic filtering before MHD pump
 - pool-type filtering (surface accumulation)

Summary



- Conceptual design of XT-ADS spallation target loop
- Confirmation of MYRRHA draft 2 fundamental properties :
 - no target window
 - compact vertical confluent flow for target formation
 - off-axis servicing
 - two pump uncoupled LBE pumping system
- Modifications to MYRRHA draft 2 :
 - boundary conditions
 - Spallation target nozzle : detached flow
 - pumps system : active pump in feeder line
 - Vacuum system
- R&D Confirmation...